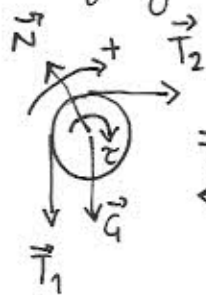
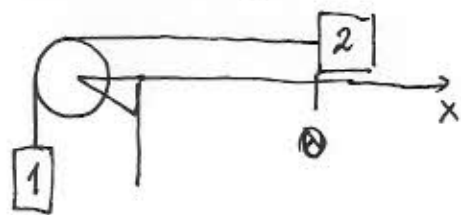
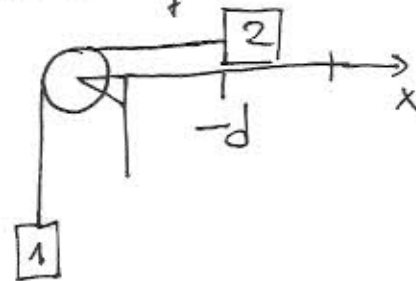


QUESTION 1

Question (a) asks for a speed, hence we are going to use the kinetic energy theorem.

INITIAL

$$v_i = 0$$

FINAL $v_f = ?$ 

$\vec{G}_1$, $\vec{N}$, $\vec{G}_2$ and $\vec{N}_2$ do not do any work. The tensions $\vec{T}_1$ and $\vec{T}_2$ do work of opposite sign in the different masses so their contribution is null. Hence:

$$W = W_{G_1} + W_{\tau} = m_1 g \cdot d - \frac{\tau_f}{R} \cdot d \quad \frac{\tau_f}{R} \text{ being the friction force because } \tau_f \text{ is the friction torque.}$$

The kinetic energy theorem reads: $\Delta K = \frac{1}{2}(m_1 + m_2)v_f^2 + \frac{1}{2}I\left(\frac{v_f}{R}\right)^2 = (m_1 g - \frac{\tau_f}{R}) \cdot d$, hence

$$v_f = \sqrt{\frac{2(m_1 g - \frac{\tau_f}{R})}{m_1 + m_2 + \frac{I}{R^2}}}$$

Question (b) asks for a time, hence we have to apply the Newtonian method.

From the force diagrams above, considering the equation along the direction of motion:

$$1) a = \frac{T_1 - m_1 g}{m_1}$$

$$2) \alpha = \frac{\tau + (T_2 - T_1) \cdot R}{I}$$

$$3) a = \frac{-T_2}{m_2}$$

On this equation, torques and moment of inertia are calculated with respect the axis of rotation. $\vec{G}$ and $\vec{N}$ do not contribute.

Knowing that $\alpha = \frac{a}{R}$, one can solve for a; at the end:

$$a = \frac{-m_1 g + \frac{\tau_f}{R}}{m_1 + m_2 + \frac{I}{R^2}}$$

Since the acceleration is constant the resulting motion is:

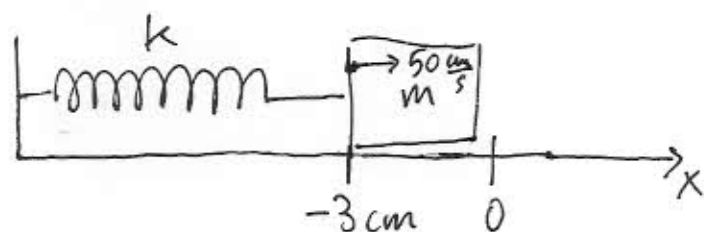
$$X(t) = X_0 + v_0 \cdot t + \frac{1}{2} a t^2$$

Assuming the initial event as the OTE, the motion becomes:

$X(t) = \frac{1}{2} a t^2$ and the time t_d at which $X(t_d) = -d$ is:

$$t_d = \sqrt{\frac{-2d}{a}} = \sqrt{\frac{2d(m_1 + m_2 + \frac{I}{R^2})}{m_1 g - \frac{\tau_f}{R}}}$$

QUESTION 2



A mass attached to a spring, with no friction, is a simple harmonic oscillator. Its motion is in general of this type:

$$X(t) = A \cdot \cos(\omega t + \varphi)$$

$$\text{where } \omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{25}{1}} = 5 \frac{\text{rad}}{\text{s}}$$

A and φ are found from the initial conditions: $X(0) = -3 \text{ cm}$ $v(0) = 50 \frac{\text{cm}}{\text{s}}$

Deriving $X(t)$ with respect time one finds $v(t) = -A\omega \cdot \sin(\omega t + \varphi)$, hence:

$$\left. \begin{aligned} X(0) = -0.03 &= A \cdot \cos(\varphi) \\ v(0) = 0.50 &= -A \cdot \omega \cdot \sin(\varphi) \end{aligned} \right\} \Rightarrow \tan(\varphi) = \frac{0.50}{0.03 \omega} \rightarrow \varphi = \tan^{-1}\left(\frac{50}{0.03 \cdot 5}\right) \approx 1.28 \text{ rad}$$

$$\text{and } A = -\frac{0.03}{\cos(1.28)} \approx -10.5 \text{ cm}$$

Answer to question (a):

$$\begin{aligned} X(t) &= -10.5 \cdot \cos(5t + 1.28) \text{ cm} \\ v(t) &= 52.5 \cdot \sin(5t + 1.28) \frac{\text{cm}}{\text{s}} \\ a(t) &= 2.63 \cdot \cos(5t + 1.28) \frac{\text{m}}{\text{s}^2} \end{aligned}$$

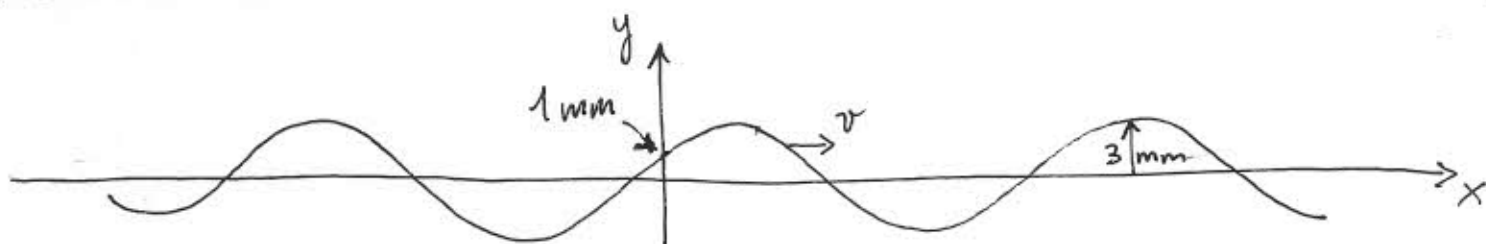
answer to question (b)

$$\begin{aligned} X_{\max} &= 10.5 \text{ cm} \\ v_{\max} &= 0.525 \frac{\text{m}}{\text{s}} \\ a_{\max} &= 2.63 \frac{\text{m}}{\text{s}^2} \end{aligned}$$

The energy of this motion can be calculated as maximum potential or kinetic energy:

$$U_{\max} = \frac{1}{2} k X_{\max}^2 = \frac{1}{2} 25 \cdot (0.105)^2 = 0.138 \text{ J}$$

$$K_{\max} = \frac{1}{2} m (A \cdot \omega)^2 = \frac{1}{2} \cdot 1 \cdot (0.105 \cdot 5)^2 = 0.138 \text{ J}$$



We suppose the wave travelling to the right.

The general expression for an harmonic wave is :

$$y(x, t) = A \cdot \sin(kx - \omega t + \varphi)$$

Let's find the parameters:

$$A = 3 \text{ mm} = 3 \cdot 10^{-3} \text{ m}$$

$$\omega = 2\pi \cdot f = 2\pi \cdot 75 = 150\pi \frac{\text{rad}}{\text{s}}$$

$$k = \frac{2\pi}{\lambda} = \frac{2\pi}{v \cdot T} = \frac{\omega}{v} \quad \text{but} \quad v = \sqrt{\frac{T}{\mu}} = \sqrt{\frac{50}{0.03}} \approx 40.8 \frac{\text{m}}{\text{s}} \quad \text{hence}$$

$$k = \frac{150\pi}{40.8} = 3.68 \cdot \pi \text{ m}^{-1}$$

$$\text{Since } y(0,0) = 1 \text{ mm} \rightarrow 1 = 3 \cdot \sin \varphi \rightarrow \varphi = \sin^{-1}\left(\frac{1}{3}\right) \approx 0.34 \text{ rad}$$

$$\text{The expression of this wave is then } y(x, t) = 3 \cdot \sin(3.68\pi \cdot x - 150\pi \cdot t + 0.34) \text{ mm}$$

The energy in 12λ is calculated as the maximum kinetic energy of a mass equal to $\mu \cdot 12 \cdot \lambda$, hence

$$E_{\text{max}} = \frac{1}{2} \mu \cdot 12 \cdot \lambda \cdot (A \cdot \omega)^2 = \frac{1}{2} 0.03 \cdot 12 \cdot \frac{2\pi}{3.68 \cdot \pi} \cdot (3 \cdot 10^{-3} \cdot 150 \cdot \pi)^2 = 0.719 \text{ J}$$

The power is

$$P = \frac{1}{2} \mu (A \cdot \omega)^2 \cdot v = \frac{1}{2} 0.03 (3 \cdot 10^{-3} \cdot 150 \pi)^2 \cdot 40.8 \approx 1.22 \text{ W}$$