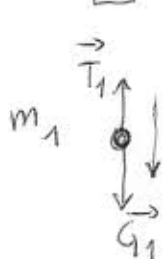
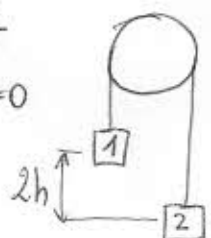


QUESTION 1

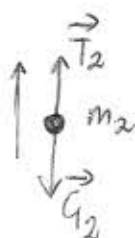
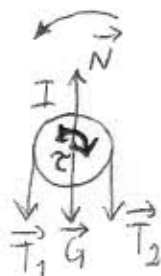
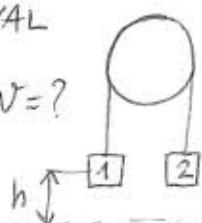
INITIAL

$$v=0$$



FINAL

$$v=?$$



$$\Delta K = W$$

$$W = W_{G1} + W_{\tau} + W_{G2} =$$

$$= m_1 g h - \tau/R \cdot h - m_2 g h$$

hence:

$$\Delta K = K_f - K_i = \frac{1}{2} m_1 v_f^2 + \frac{1}{2} m_2 v_f^2 + \frac{1}{2} I \left(\frac{v_f}{R} \right)^2 =$$

$$= [(m_1 - m_2)g - \tau/R] h$$

The works of T_1 and T_2 sum to zero because T_1 and T_2 are internal forces. $\vec{N}$ and $\vec{G}$ do not produce work. The resulting speed is:

$$v_f = \sqrt{\frac{2[(m_1 - m_2)g - \tau/R] \cdot h}{m_1 + m_2 + \frac{I}{R^2}}}$$

To answer question (b) one needs to apply the Newton's method. Following the reference systems indicated in the force diagrams above, the 3 equations are:

$$1) a = \frac{m_1 g - T_1}{m_1}$$

knowing that $a = \frac{a}{R}$ one can solve for a :

$$2) a = \frac{-\tau + (T_1 - T_2) \cdot R}{I}$$

$$a = \frac{(m_1 - m_2)g - \tau/R}{m_1 + m_2 + \frac{I}{R^2}} \rightarrow \text{Since } a = \text{constant the motion is:}$$

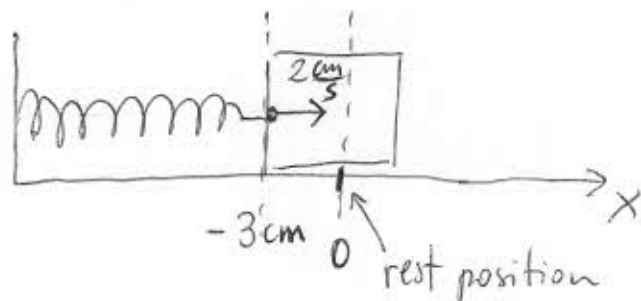
$$3) a = \frac{T_2 - m_2 g}{m_2}$$

$$x = x_0 + v_0 \cdot t + \frac{1}{2} a t^2$$

Considering the mass ①, setting the OTE at its initial position, the motion is $x_1 = \frac{1}{2} a t^2$. The time t_h ~~to~~ required to travel a distance of h is then: $t = \sqrt{\frac{2h}{a}} \rightarrow$

$$\rightarrow t = \sqrt{\frac{2h(m_1 + m_2 + \frac{I}{R^2})}{(m_1 - m_2)g - \tau/R}}$$

QUESTION 2



The general expression of the motion is:

$$x(t) = A \cdot \cos(\omega t + \varphi)$$

$$\text{where } \omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{25}{1}} = 5 \frac{\text{rad}}{\text{s}}$$

A and φ are found from the conditions on position and speed, which is:

$$v(t) = -A\omega \sin(\omega t + \varphi)$$

Assuming that the OTE is the one indicated in the picture:

$$\begin{cases} -0.03 = A \cdot \cos(\varphi) \\ 0.02 = -A \cdot \omega \cdot \sin(\varphi) \end{cases} \rightarrow \tan(\varphi) = \frac{0.02}{0.03 \cdot \omega} \Rightarrow \varphi = \tan^{-1}\left(\frac{2}{15}\right) = 0.133 \text{ rad}$$

and $A = -\frac{0.03}{\cos(0.133)} = -3.03 \text{ cm}$

The displacement is then $x(t) = -3.03 \cdot \cos(5 \cdot t + 0.133) \text{ cm}$

Speed and acceleration are $v(t) = 15.15 \sin(5 \cdot t + 0.133) \frac{\text{cm}}{\text{s}}$

$$a(t) = 75.75 \cos(5 \cdot t + 0.133) \frac{\text{cm}}{\text{s}^2}$$

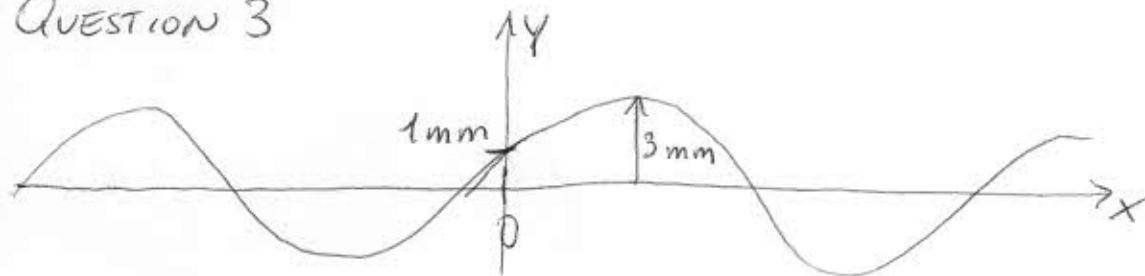
Maximum speed is $15.15 \frac{\text{cm}}{\text{s}}$ and maximum acceleration $75.75 \frac{\text{cm}}{\text{s}^2}$

The energy of the motion is $E = K_{\text{max}} = U_{\text{max}}$

$$K_{\text{max}} = \frac{1}{2} m v_{\text{max}}^2 = \frac{1}{2} \cdot 1 \cdot 0.1515^2 = 0.0115 \text{ J}$$

QUESTION 3

3



The general expression is $Y(x,t) = A \cdot \sin(k \cdot x - \omega t + \varphi)$

Some of the parameters are almost ready to be known, like ω :

$$\omega = 2\pi f = 2\pi \cdot 75 = 150\pi \frac{\text{rad}}{\text{s}}$$

$$A = 3 \text{ mm} = 3 \cdot 10^{-3} \text{ m}$$

k is known through the speed. $v = \sqrt{\frac{I}{\mu}} = \sqrt{\frac{50}{0.03}} \approx 40.8 \frac{\text{m}}{\text{s}}$ and since

$$v = \frac{\lambda}{T} = \frac{\omega}{k} \rightarrow k = \frac{\omega}{v} = \frac{150\pi}{40.8} = 3.68\pi \text{ m}^{-1}. \text{ For the last parameter, } \varphi:$$

$$Y(0,0) = 1 = 3 \sin(\varphi) \Rightarrow \varphi = \sin^{-1}\left(\frac{1}{3}\right) \approx 0.34 \text{ rad. The wave is:}$$

$$Y(x,t) = 3 \cdot \sin(3.68\pi \cdot x - 150\pi \cdot t + 0.34) \text{ mm}$$

The energy in 1λ is $E_\lambda = \frac{1}{2} \mu \cdot \lambda (A \cdot \omega)^2 = \frac{1}{2} \mu \frac{2\pi}{k} (A \cdot \omega)^2 =$

$$= 0.03 \cdot \frac{\pi}{3.68 \cdot \pi} \cdot (3 \cdot 10^{-3} \cdot 150 \cdot \pi)^2 = 16.3 \text{ mJ}$$

In 12λ the result for the energy is $12 \cdot 16.3 \text{ mJ} = 195.6 \text{ mJ}$

The power is: $P = \frac{1}{2} \mu (A \omega)^2 \cdot v = \frac{1}{2} 0.03 (3 \cdot 10^{-3} \cdot 150 \cdot \pi)^2 \cdot 40.8 \approx 1.22 \text{ W}$