

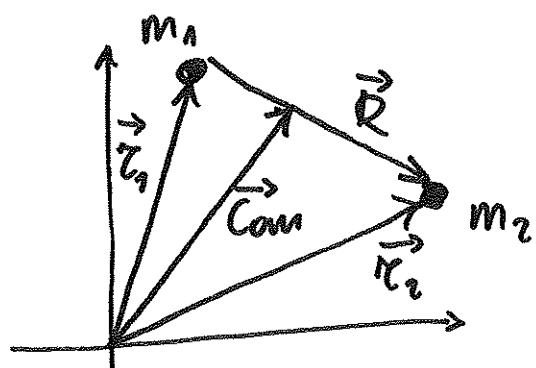
## GW from a binary in a circular orbit

We have 2 point-like objects of masses  $m_1$  and  $m_2$  in a circular orbit around the centre of mass of the system.

The positions of the two masses are given by  $\vec{r}_1(t)$  and  $\vec{r}_2(t)$ . We change coordinates introducing the vector position of the centre of mass  $\vec{\text{Com}}$  and relative distance  $\vec{R}(t)$ :

$$\vec{\text{Com}} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2}$$

$$\vec{R} = \vec{r}_2 - \vec{r}_1$$

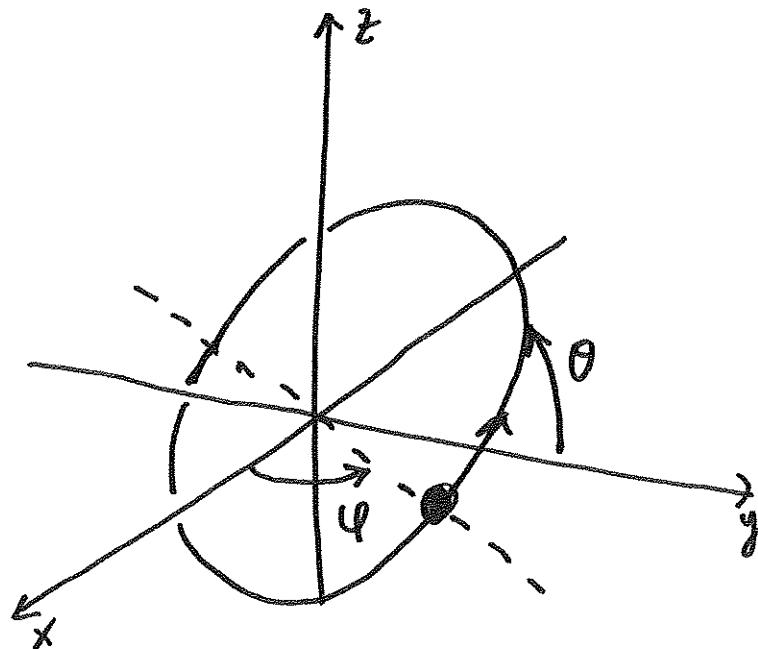
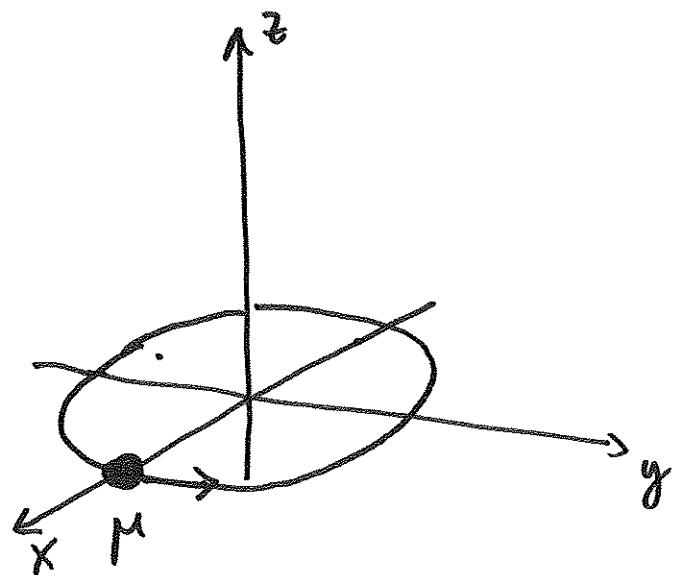


The system is isolated so,  $\vec{\text{Com}}$  we can assume that is constant with time. The dynamic is reduced to a single point of mass  $\mu = \frac{m_1 m_2}{m_1 + m_2}$  orbiting

at constant distance  $|\vec{R}|$  around the origin of coordinates 0.

We consider the orbit laying on the x-y plane.

The GW propagates in the z direction, positive:



The kinematics of the particle on the plane is given by: (2)

$$\vec{R} = R \begin{pmatrix} \cos(\omega t) \\ \sin(\omega t) \\ 0 \end{pmatrix} = R \begin{pmatrix} c_w \\ s_w \\ 0 \end{pmatrix} \quad \text{we use a simplified notation}$$

of the trigonometric  
functions  $\sin$  and  $\cos$ .

To describe a general circular orbit we have to introduce 2 rotation matrices,  $R_\theta$  and  $R_\varphi$ :

$$R_\theta = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_\theta & -s_\theta \\ 0 & s_\theta & c_\theta \end{pmatrix} \quad R_\varphi = \begin{pmatrix} c_\varphi & -s_\varphi & 0 \\ s_\varphi & c_\varphi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

the tilted orbit kinematics is then:

$$\vec{R}' = R_\theta \cdot \vec{R} = R \begin{pmatrix} c_w \\ c_\theta \cdot s_w \\ s_\theta \cdot s_w \end{pmatrix} \quad \vec{R}'' = R_\varphi \cdot \vec{R}' = R \begin{pmatrix} c_\varphi \cdot c_w - s_\varphi \cdot c_\theta \cdot s_w \\ s_\varphi \cdot c_w + c_\varphi \cdot c_\theta \cdot s_w \\ s_\theta \cdot s_w \end{pmatrix}$$

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The quadrupole radiation expression is

$$h_{ij}^{TT}(t, \vec{x}) = \frac{1}{2} \frac{2G}{c^4} \Lambda_{ij,kl} \ddot{\mathcal{E}}^{kl} \quad \text{where:}$$

$$\mathcal{M}^{kl} = \frac{1}{c^2} \int d^3x' x^k \cdot x^l \cdot T^{00} = \sum_i^N x_i^k \cdot x_i^l \cdot m_i$$

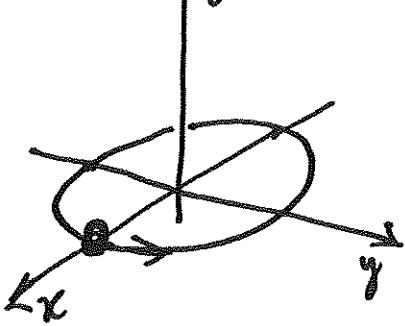
If  $\hat{n} = \hat{k}$  then:

$$\Lambda_{ij,kl} \ddot{\mathcal{E}}^{kl} = \begin{pmatrix} \frac{\ddot{x}_{ii} \cdot \ddot{x}_{jj}}{2} & \ddot{x}_{ij} & 0 \\ \ddot{x}_{ij} & -\frac{\ddot{x}_{ii} \cdot \ddot{x}_{jj}}{2} & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

(3)

Now we study different cases corresponding at different orientations of the orbit.

Case ①  $\theta = \varphi = 0$   $\vec{r}'' = \vec{r} = R \begin{pmatrix} c_w \\ s_w \\ 0 \end{pmatrix}$   $\mathcal{H}_{11} = +\mu R c_w^2 = +\mu \frac{R^2}{2} (1 + c_{2w})$



$$\mathcal{H}_{12} = -\mu R c_w s_w = \mathcal{H}_{22} = +\mu \frac{R^2}{2} (1 - c_{2w})$$

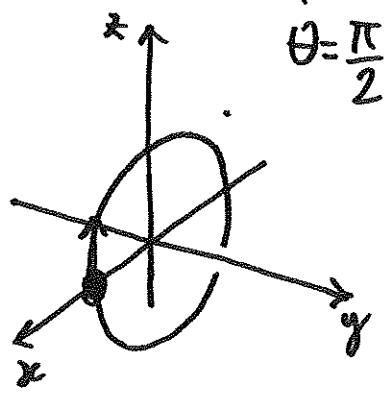
$$= \mu \frac{R^2}{2} s_{2w} \quad \text{So}$$

$$h^+ = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{4} 4w^2 c_{2w} \cdot 2 = -\frac{1}{2} \frac{4G}{C^4} \mu R^2 w^2 c_{2w}$$

$$h^X = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{2} 4w^2 s_{2w} = -\frac{1}{2} \frac{4G}{C^4} \mu R^2 w^2 s_{2w}$$

The solution shows the 2 polarizations present with the same amplitude and out of phase  $\frac{\pi}{2}$ . It means the radiation is perfectly circularly polarized.

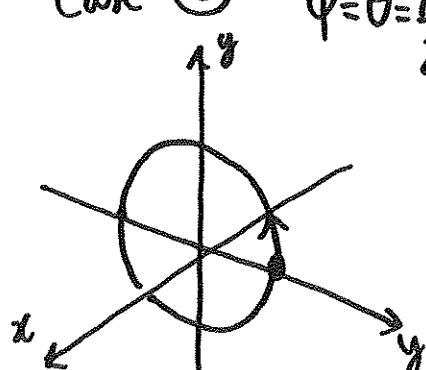
Case ②  $\varphi = 0$   $\vec{r}'' = R \begin{pmatrix} c_w \\ 0 \\ s_w \end{pmatrix}$   $\mathcal{H}_{11} = \mu \frac{R^2}{2} (1 + c_{2w})$   
 $\theta = \frac{\pi}{2}$   $\mathcal{H}_{22} = 0 \quad \mathcal{H}_{12} = 0$



$$h^+ = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{4} 4w^2 c_{2w} = -\frac{1}{2} \frac{2G}{C^4} \mu R^2 w^2 c_{2w}$$

$$h^X = 0$$

Case ③  $\varphi = \theta = \frac{\pi}{2}$   $\vec{r}'' = R \begin{pmatrix} 0 \\ c_w \\ s_w \end{pmatrix}$   $\mathcal{H}_{11} = \mathcal{H}_{12} = 0$   
 $\mathcal{H}_{22} = \mu \frac{R^2}{2} (1 + c_{2w})$



$$h^+ = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{4} 4w^2 c_{2w} = -\frac{1}{2} \frac{2G}{C^4} \mu R^2 w^2 c_{2w}$$

$$h^X = 0$$

(4)

Case ④

$$\theta = \frac{\pi}{2}$$

$$\rho = \frac{\pi}{4}$$

$$\vec{r}'' = R \begin{pmatrix} \frac{cw}{\sqrt{2}} \\ \frac{cw}{\sqrt{2}} \\ 0w \end{pmatrix}$$

$$\partial C_{11} = \mu \frac{R^2}{2} \frac{1}{2} (1 + c_{2w}) = \partial C_{22}$$

$$= \partial C_{12} \quad \text{So,}$$

$$h^+ = 0$$

$$h^x = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{4} 4w^2 c_{2w} = -\frac{1}{2} \frac{2G}{C^4} \mu R^2 w^2 c_{2w}$$

Cases ③ and ④ should come from the rotation of the "detector" around the z axis by a suitable angle  $\eta$ .  
The rotation matrix is:

$$R_\eta = \begin{pmatrix} c_\eta & s_\eta & 0 \\ -s_\eta & c_\eta & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{The tensor } h_{ij} \text{ changes into } R^T \tilde{h} R$$

$$\tilde{h} \cdot R = \begin{pmatrix} h^+ & h^x & 0 \\ h^x & -h^+ & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} c & 0 & 0 \\ -s & c & 0 \\ 0 & 0 & 1 \end{pmatrix} =$$

$$R_\eta^T = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} h^+ - h^x s & h^+ + h^x c & 0 \\ h^x s + h^c & h^x - h^c & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$R^T \tilde{h} R = \begin{pmatrix} h^{+2} - h^{x2} - h^2 s - h^2 c & h^+ c + h^x c^2 - h^x s^2 + h^c s & 0 \\ h^+ c s - h^x s^2 + h^c s + h^x c^2 & h^x s^2 + h^c s + h^c s - h^c c^2 & 0 \\ 0 & 0 & 0 \end{pmatrix} =$$

$$= \begin{pmatrix} h^+ c_{2\eta} - h^x s_{2\eta} & h^x c_{2\eta} + h^+ s_{2\eta} & 0 \\ h^x c_{2\eta} + h^+ s_{2\eta} & -h^+ c_{2\eta} + h^x s_{2\eta} & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

A rotation of  $-45^\circ$  produces a change of polarization from  $h^X$  to  $h^+$ . (5)

Let's see a rotation around the  $x$ -axis.

$$R_x = \begin{pmatrix} 1 & 0 & 0 \\ 0 & C_x & S_x \\ 0 & -S_x & C_x \end{pmatrix} \quad \tilde{h} \cdot R_x = \begin{pmatrix} h^+ & h^X & 0 \\ h^X & -h^+ & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & C_x & S_x \\ 0 & -S_x & C_x \end{pmatrix} = \begin{pmatrix} h^+ & h^X C_x & h^X S_x \\ h^X & -h^+ C_x & -h^+ S_x \\ 0 & 0 & 0 \end{pmatrix}$$

$$R_x^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & C_x & -S_x \\ 0 & S_x & C_x \end{pmatrix} \quad R_x^T \tilde{h} R_x = \begin{pmatrix} h^+ & h^X C_x & h^X S_x \\ h^X & -h^+ C_x^2 & -h^+ S_x C_x \\ h^X S_x & -h^+ C_x S_x & -h^+ S_x^2 \end{pmatrix}$$

For  $x = \frac{\pi}{2}$  one has:  $\begin{pmatrix} h^+ & 0 & h^X \\ 0 & 0 & 0 \\ h^X & 0 & -h^+ \end{pmatrix}$

Case ⑤

$$\begin{aligned} \varphi &= 0 \\ \theta &= \frac{\pi}{4} \end{aligned}$$

$$\vec{r}'' = R \begin{pmatrix} C_w \\ \frac{S_w}{\sqrt{2}} \\ \frac{S_w}{\sqrt{2}} \end{pmatrix}$$

$$\tilde{h}_{11} = \mu \frac{R^2}{2} (1 + C_{2w})$$

$$\tilde{h}_{22} = \mu \frac{R^2}{4} (1 - C_{2w})$$

$$\tilde{h}_{12} = \mu \frac{R^2}{2\sqrt{2}} S_{2w}$$

$$h^+ = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{2} \frac{4w^2}{2} C_{2w} \left( \frac{1}{2} + \frac{1}{2} \right) = -\frac{1}{2} \frac{4G}{2C^4} \mu R^2 w^2 C_{2w}$$

$$h^X = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{2\sqrt{2}} 4w^2 \cdot \frac{1}{2} S_{2w} = -\frac{1}{2} \frac{4G}{\sqrt{2}C^4} \mu R^2 w^2 \cdot \frac{1}{2} S_{2w}$$

Case ⑥

$$\begin{aligned} \varphi &= 0 \\ \theta &\neq \frac{\pi}{4} \end{aligned}$$

$$\vec{r}'' = R \begin{pmatrix} C_w & 0 & 0 \\ 0 & S_w & 0 \\ 0 & 0 & S_w \end{pmatrix}$$

$$\tilde{h}_{11} = \mu \frac{R^2}{2} (1 + C_{2w}) \quad \tilde{h}_{22} = \mu \frac{R^2}{2} C_\theta^2 (1 - C_{2w})$$

$$\tilde{h}_{12} = \mu \frac{R^2}{2} C_\theta S_{2w}$$

$$h^+ = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{2} \frac{4w^2}{2} C_{2w} (1 + C_\theta^2) = -\frac{1}{2} \frac{4G}{C^4} \mu R^2 w^2 \left( \frac{1 + C_\theta^2}{2} \right) \cdot C_{2w}$$

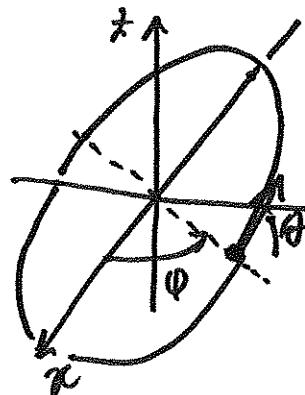
$$h^X = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{2} 4w^2 \cdot C_\theta S_{2w} = -\frac{1}{2} \frac{4G}{C^4} \mu R^2 w^2 \cdot C_\theta \cdot S_{2w}$$

(6)

A remarkable result of this case is the fact that the ratio between the amplitudes gives the inclination  $\theta$  of the orbit

$$\frac{\sqrt{h^+ h^{++}}}{\sqrt{h^X h^{XX}}} = \frac{1 + \cos^2 \theta}{2 \cos \theta}$$

Case ⑦ this is the general case



$$\vec{r}'' = R \begin{pmatrix} c_\phi \cdot c_w - s_\phi \cdot c_\theta \cdot s_w \\ s_\phi \cdot c_w + c_\phi \cdot c_\theta \cdot s_w \\ s_\theta \cdot s_w \end{pmatrix}$$

$$\partial_{11} = \mu \frac{R^2}{2} \left[ c_\phi^2 (1 + c_{2w}) + s_\phi^2 c_\theta^2 (1 - c_{2w}) - [s_\phi c_\theta] s_{2w} \right]$$

$$\partial_{22} = \mu \frac{R^2}{2} \left[ s_\phi^2 (1 + c_{2w}) + c_\phi^2 c_\theta^2 (1 - c_{2w}) + s_\phi c_\theta s_{2w} \right]$$

$$h^+ = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{2} 4w^2 \frac{1}{2} \left[ c_{2w} (c_\phi^2 - s_\phi^2 c_\theta^2 - s_\phi^2 + c_\phi^2 c_\theta^2) - s_{2w} (s_{2\phi} \cdot c_\theta \cdot 2) \right] =$$

$$= -\frac{1}{2} \frac{2G}{C^4} \mu R^2 w^2 \left[ c_{2w} (c_{2\phi} + c_\theta^2 \cdot c_{2\phi}) - s_{2w} (2 \cdot s_{2\phi} \cdot c_\theta) \right] =$$

$$= -\frac{i}{2} \frac{2G}{C^4} \mu R^2 w^2 \left[ (1 + c_\theta^2) \cdot c_{2\phi} \cdot c_{2w} - c_\theta \cdot s_{2\phi} \cdot 2 \cdot s_{2w} \right]$$

$$\partial_{12} = \mu \frac{R^2}{2} \left[ \frac{1}{2} s_{2\phi} (1 + c_{2w}) - \frac{1}{2} s_{2\phi} c_\theta^2 (1 - c_{2w}) + (c_\phi^2 c_\theta - s_\phi^2 c_\theta) s_{2w} \right]$$

$$h^X = -\frac{1}{2} \frac{2G}{C^4} \mu \frac{R^2}{2} 4w^2 \left[ c_{2w} \left( \frac{1}{2} s_{2\phi} + \frac{1}{2} s_{2\phi} c_\theta^2 \right) + c_\theta (s_{2\phi} \cdot c_{2w}) \right] =$$

$$= -\frac{1}{2} \frac{2G}{C^4} \mu R^2 w^2 \left[ (1 + c_\theta^2) \cdot s_{2\phi} \cdot c_{2w} + c_\theta \cdot c_{2\phi} \cdot 2 s_{2w} \right]$$

$$h^+ = -\frac{1}{2} \frac{4G}{C^4} \mu R_w^2 w^2 \left[ c_{2\psi} \cdot \frac{1+c_\theta^2}{2} c_{2w} - s_{2\psi} \cdot c_\theta \cdot s_{2w} \right]$$

$$h^\times = -\frac{1}{2} \frac{4G}{C^4} \mu R_w^2 w^2 \left[ s_{2\psi} \cdot \frac{1+c_\theta^2}{2} c_{2w} + c_{2\psi} \cdot c_\theta \cdot s_{2w} \right]$$

which is case ⑤ rotated by an angle  $\psi$  around the z-axis.  
 Let's see if  $h^+$  and  $h^\times$  are still in quadrature. Multiplying  
 the 2 [ ] we have:

$$\frac{s_{4\psi}}{2} \cdot \left( \frac{1+c_\theta^2}{2} \right)^2 c_{2w}^2 - \frac{s_{4\psi}}{2} \cdot c_\theta^2 s_{2w}^2 + O(c_{2w} \cdot s_{2w}) \quad \text{the DC part is:}$$

$$\frac{s_{4\psi}}{2} \frac{1}{2} \left[ \frac{(1+c_\theta^2)^2}{4} - c_\theta^2 \right] \text{ which is 0 only if } \theta=0.$$